



#### Latest PPP Efforts at UNB (2007-2008)

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- □ Impact of L2C on PPP
- **PPP-Based** Ionosphere Activity Monitoring
- □ Wide Area Differential GPS Precise Point Positioning (WADGPS-PPP)
- Ambiguity Resolution
- Generation Future Work
- **D**Topic for Discussion











Additional measurements and their signal-to-noise ratio



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Comparison of iono-free code M+N using P2 and L2C (all IIR-M)



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#### Additional measurements and their elevation angle



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Static PPP run using L2C and L2P(Y) (horizontal)



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Local Ionospheric Delay Model with a Single Receiver

$$\Phi_{gf} = \Phi_1 - \Phi_2 = I + \lambda_{gf} N'_{gf} + e_{gf}$$
$$N'_{gf} = N_{gf} + \frac{dpb_r - dpb^s}{\lambda_{gf}}$$
$$I = M(I_{v,0} + \Delta\phi\nabla I_{v,\phi} + \Delta\lambda\nabla I_{v,\lambda})$$



# PPP-Based Ionospheric Activity Monitoring



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#### Advantages

- Stand alone receiver
- Pure carrier-phase based estimations
- Static or kinematic mode
- Suitable for real time applications

#### Drawbacks

- Strong geometry dependence
- Not adequate for iono map generation
- Convergence time issue



#### WADGPS-PPP





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## WADGPS-PPP: Orbit and Clock Corrections





#### **WADGPS-PPP:Positioning Results**





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#### **Ambiguity Resolution**









#### □ Receiver Phase Bias Calibration







#### Receiver Phase Bias Calibration



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□ Satellite Phase Bias Calibration (widelane example)



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- Analysis of L2C signal performance in more challenging environments (high multipath, less visibility, kinematic)
- □ Impact of shell height and degree of polynomial on ionosphere model
- GAPS Enhancements
  - Translation from MatLab to C++
  - Improved computational performance
  - Modernization-ready (handling of RINEX 3.00)





#### □ Standard Data Sets for PPP Software Testing ?

- Purposes
  - Validate new software
  - Compare software / implementation strategies
  - Test new processing strategies
  - Identify limitations of PPP
- Elements of comparison
  - Convergence time
  - Achievable accuracy
  - Precision vs accuracy
- Selection of sets
  - Static / kinematic
  - Reference coordinates, data rate, IGS products to use, etc.



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